# **Cole Thomas Fenner**

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### **Professional Summary**

Detail-oriented Robotics Engineer with expertise in mechanical design, modeling, and hands-on prototyping. Proven leadership in competitive robotics and research-driven system optimization, with a strong foundation in 3D modeling, CNC machining, and ROS.

## Education

### Oregon State University— Corvallis, OR

Master of Science in Robotics (GPA: 4.00) | Graduated: 2025

- Thesis: Modeling and predicting tethered projectile motion using an Odrive controller.
- Research Focus: Adjoint matrices in group-based modeling, compliant Kinova arm control, optimized path planning, and 3D robotic simulation.

### Bachelor of Science in Mechanical Engineering (GPA: 3.89) | Graduated: 2024

- Focus: GD&T, Composite Manufacturing, 3D Modeling, Design
- Awards: OSU Finley Scholarship, Intel Scholarship, Dean's List, Honor Roll

### Portland Community College — Portland, OR (GPA: 4.00)

Slender Game Modeling, CNC Manufacturing, Summer Baccalaureate Coursework

# **Technical Skills**

- Programming: Python, ROS, Matlab, Gazebo, HTML
- 3D Modeling: Fusion 360, Autodesk Inventor, AutoCAD, SolidWorks, Siemens NX
- Prototyping: CNC machining, 3D printing, laser cutting, welding
- Engineering: GD&T, adjoint matrix coding, composite manufacturing

# **Engineering Experience**

#### First Robotics Competition Team Captain, Shockwave 4488

#### Aug 2017 – Mar 2021

- Designed, prototyped, and manufactured competition robots using Fusion 360 and CNC machining.
- Led a team of 30+ members to achieve recognition, including:
  - > 2018 World Galileo Division Champion and Innovation in Control Award.
  - > 2019 Industrial Design Award and Pacific Northwest Championship finalist.
- Led outreach initiatives, adapting toys for children with disabilities to improve accessibility.

#### Graduate Teaching Assistant, Oregon State University

Sept 2024 – Present

Assisted with engineering coursework by grading, proctoring exams, and holding student office hours.

### Design Engineering Intern, MEGI Consulting

June 2022 – Sept 2022

- Developed 3D models of industrial paper mill systems using point cloud data.
- Updated piping and electrical systems in AutoCAD to improve infrastructure adaptability. (P&ID)

#### SAE Baja Senior Project, Oregon State University

Sept 2023 – March 2024

- Led the reverse engineering and manufacturing of a limited-slip differential gearbox for CNC production.
- Utilized 3D modeling software to optimize design for manufacturability and performance.
- Conducted FEA to optimize stress tolerances, enhancing gearbox durability.
- Collaborated with a multidisciplinary team to integrate the gearbox into the SAE Baja vehicle.

# Projects

### **Capstan Drive Robotic Arm**

Independent Project

Engineered a robotic arm using a capstan drive system, improving movement precision and force feedback.

#### **Octocanum Drive System**

Independent Project

 Designed and built a mechanical octocanum drive system, compactly integrated around a 2x1 aluminum bar. Used rapid 3D printing for prototyping and design optimization.

#### Swerve Drive System

Team Project- 4488 Shockwave

- Designed and fabricated a custom differential gearbox, optimizing performance while ensuring a compact corner fit.
- Integrated custom-designed subassemblies, including intakes, funnels, arm manipulators, and shooters.

# **Honors & Activities**

- Chess Achievements: Founded high school chess team; multiple regional and state placements.
- \* Tennis Team Captain: Led Glencoe High School team, earning district quarterfinalist honors.
- Officer, College Club Tennis Team: Coordinate practices and competitions as part of the leadership team for Oregon State University's club tennis team.
- FRC Recognitions: Earned multiple FRC awards, including World Championship Galileo Division Winner, Innovation in Control Award, and Industrial Design Award.
- Slack Belt in Tae Kwon Do: Demonstrated discipline and leadership through mentoring students.